

# Applicazioni del Principio di indifferenza Materiali

Nel caso della velocità e del suo gradiente, fatti da un altro osservatore, si ha; poiché  $\underline{x} = R \underline{x}'$ ,

$$\underline{v}' = \frac{d\underline{x}'}{dt} = \dot{\underline{R}}^T \underline{x}' + \underline{R}^T \dot{\underline{x}'} = \dot{\underline{R}}^T \underline{R} \underline{x}' + \underline{R}^T \underline{v} . \quad (1)$$

Dunque  $\underline{v}'$  non si trasforma semplicemente in  $\underline{R}^T \underline{v}$ , ma è influenzato anche dalla scelta del tensore anti-simmetrico  $\dot{\underline{R}}^T \underline{R}$ ; quindi  $\underline{v}$  non può intervenire direttamente in un'equazione costitutiva. Per il suo gradiente si ha:

$$\begin{aligned} \nabla_{\underline{x}'} \underline{v}' &= \nabla_{\underline{x}'} (\dot{\underline{R}}^T \underline{R} \underline{x}' + \underline{R}^T \underline{v}) = \dot{\underline{R}}^T \underline{R} \nabla_{\underline{x}'} \underline{x}' + \underline{R}^T \nabla_{\underline{x}'} \underline{v} = \\ &= \dot{\underline{R}}^T \underline{R} \underline{I} + \underline{R}^T \nabla_{\underline{x}'} \underline{v} \frac{\partial \underline{x}'}{\partial \underline{x}'} = \dot{\underline{R}}^T \underline{R} + \underline{R}^T \nabla_{\underline{x}'} \underline{v} \underline{R} = \\ &= \dot{\underline{R}}^T \underline{R} + \underline{R}^T \underline{W} \underline{R} + \underline{R}^T \underline{D} \underline{R} , \end{aligned} \quad (2)$$

dove abbiamo usato la decomposizione del  $\nabla \underline{v}$  nella velocità di deformazione  $\underline{D}$  e nella volatilità  $\underline{W}$ . Dunque:

$$\underline{D}' = \underline{R}^T \underline{D} \underline{R} \quad \text{e} \quad \underline{W}' = \dot{\underline{R}}^T \underline{R} + \underline{R}^T \underline{W} \underline{R} , \quad (3)$$

poiché  $\dot{\underline{R}}^T \underline{R} = -(\dot{\underline{R}}^T \underline{R})^T$  d'après la relazione  $\underline{R}^T \underline{R} = \underline{I}$ .

Anciò solo  $\underline{D}$  può comparire nelle equazioni costitutive.

$$(4.32) \text{, if } h_j \quad T = F^c \quad | \quad T = F^{-1}, \text{ ergo } \text{in hypothesis}$$

$$T_{ij} = J + \frac{\partial X_A}{\partial x_j} \quad ; \quad S = F^{-1} T = F^{-1} = (-1)^{i+j} \frac{\det F^{(ij)}}{\det F}$$

$$\frac{\partial x}{\partial X} = F^{-1} = \begin{pmatrix} e^t & 0 & (e^t - 1) \\ 0 & 1 & (e^t - e^{-t}) \\ 0 & 0 & (1 + 3tX_3^2) \end{pmatrix} \Rightarrow J = (1 + 3tX_3^2)e^t > 0$$

$$F^c = \begin{pmatrix} (1 + 3tX_3^2)e^t & 0 & 0 \\ 0 & e^t(1 + 3tX_3^2) & 0 \\ (1 - e^t) - (e^{2t} - 1) & e^t & \end{pmatrix} \Rightarrow$$

$$\Rightarrow T = F^c = \begin{pmatrix} (1 + 3tX_3^2)3x_2e^t & e^t(1 + 3tX_3^2)x_3 & (x_1 - e^t) \\ 5x_3e^t & (1 + 3tX_3^2)(x_2 - (e^{2t} - 1)) & T_{13} \\ x_2(e^{3t} - 1) & T_{23} & \end{pmatrix}$$

$$\begin{pmatrix} x_1(1 + 3tX_3^2) & x_2e^t(1 + 3tX_3^2) & 7x_1e^t \\ T_{12} & T_{22} & T_{32} \\ T_{13} & T_{23} & T_{33} \end{pmatrix}$$

$$\begin{cases} T_{11} = (1 + 3tX_3^2)3[x_2e^t + x_3(1 - e^{-2t})] + (1 - e^t)[x_1e^t + x_3(e^t - 1)] \\ T_{12} = (1 - e^{2t})[x_1e^t + x_3(e^t - 1)] + (1 + 3tX_3^2)e^t(x_2 + tX_3^2) \end{cases}$$

(x co., wld in urendo 1-e(4.57) del resto uff uerdano).

$$\begin{cases} T_{13} = x_1e^{2t} + x_3e^t(e^t - 1) ; T_{23} = e^tx_2 + x_3(e^{2t} - 1) \\ T_{21} = (1 + 3tX_3^2)(x_3 + tX_3^2) + (1 - e^t)[x_2 + x_3(e^t - e^{-t})] \\ T_{22} = (1 - e^{2t})[x_2 + x_3(e^t - e^{-t})] + 5(1 + 3tX_3^2)(x_3 + tX_3^2) \end{cases} \xrightarrow{\text{red p. 20}}$$

$$F^{-1} = J^{-1} F^{CT} = (1+3tX_3)^{-1} e^{-t} F^{CT} = \begin{pmatrix} e^{-t} & 0 & \frac{e^{-t}(1-e^t)}{(1+3tX_3)^2 t^2} \\ 0 & 1 & \frac{-e^t + e^{-t}}{1+3tX_3^2} \\ 0 & 0 & (1+3tX_3)^{-1} \end{pmatrix}$$

$$\underline{X} = F^{-1} \underline{x} \quad \begin{cases} X_1 = (F^{-1})_{11} x_1 \\ X_2 = (F^{-1})_{21} x_1 \\ X_3 = (F^{-1})_{31} x_1 \end{cases}$$

$$S_{11} = (F^{-1} T)_{11} = e^{-t} T_{11} + \cancel{e^t(1-e^t)} (1-e^t) J^{-1} T_{31}$$

$$S_{12} = e^{-t} T_{12} + (1-e^t) J^{-1} T_{32} = S_{21}$$

$$S_{13} = e^{-t} T_{13} + (1-e^t) J^{-1} T_{33} = S_{31}$$

$$S_{22} = T_{22} + (1-e^t) J^{-1} T_{32}$$

$$S_{23} = T_{23} + (1-e^t) J^{-1} T_{33} = S_{32}$$

$$S_{33} = (1+3tX_3)^{-1} T_{33}$$

$$(ii) \quad S_* \underline{b} = S_* \underline{d} - D \nabla \underline{T} \Rightarrow \underline{b} = \underline{d} - \frac{1}{S_*} D \nabla \underline{T}$$

$$\underline{v} = \begin{pmatrix} X_1 e^t + X_3 e^t \\ X_3 (e^t + e^{-t}) \\ X_3^3 \end{pmatrix} = \begin{pmatrix} (X_1 + X_3) e^t \\ X_3 (e^t + e^{-t}) \\ X_3^3 \end{pmatrix}, \quad \underline{d} = \begin{pmatrix} (X_1 + X_3) e^t \\ X_3 (e^t - e^{-t}) \\ 0 \end{pmatrix}$$

$$\left\{ \begin{array}{l} T_{31} = [(1+3+x_3^2) + 7(1-e^t)] [x_1 e^t + x_3(e^t-1)] \\ T_{32} = 7(1-e^{2t}) [x_1 e^t + x_3(e^t-1)] + (1+3+x_3^2) [e^t x_2 + x_1(e^{2t}-1)] \\ T_{33} = 7e^t [x_1 e^t + x_3(e^t-1)] \end{array} \right.$$

$$\text{Quindi } (\text{Div } T)_1 = \frac{\partial T_{11}}{\partial x_1} = e^t(1-e^t) + 0 + e^t(e^t-1) = 0$$

$$(\text{Div } T)_2 = \frac{\partial T_{21}}{\partial x_1} = \frac{\partial T_{21}}{\partial x_1} + \frac{\partial T_{22}}{\partial x_2} + \frac{\partial T_{23}}{\partial x_3} = 0 + (1-e^{2t}) + (e^{2t}-1) = 0$$

$$(\text{Div } T)_3 = \frac{\partial T_{31}}{\partial x_1} = e^t - [(1+3+x_3^2) + 7(1-e^t)] + e^t(1+3+x_3^2) + 7e^t(e^t-1) = e^t [2(1+3+x_3^2) + 7(1-e^t) + 7(e^t-1)] = 2e^t(1+3+x_3^2).$$

$$\text{esr } b_1 = d_1 - \frac{1}{g_*} (\text{Div } T)_1 = (x_1 + x_3) e^t$$

$$b_2 = d_2 - g_*^{-1} (\text{Div } T)_2 = x_3 (e^t - e^{-t})$$

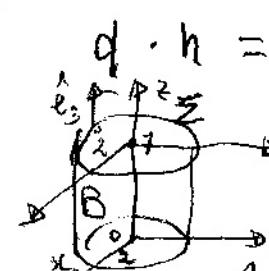
$$b_3 = d_3 - g_*^{-1} (\text{Div } T)_3 = -\frac{2}{g_*} e^t (1+3+x_3^2)$$

$$(4.35) \text{(ii)} \text{ La superficie è esterna: } \hat{\mathbf{e}}^\perp \cdot \hat{\mathbf{n}} = \frac{\partial x^1}{\xi} + \frac{\partial x^2}{\xi} \xi_1 + \dots = 0 \quad 21$$

$$\Rightarrow D\varphi = \left( \frac{x_1}{2}, \frac{x_2}{2}, 0 \right) \quad e \quad |D\varphi| = \sqrt{\frac{x_1^2}{\xi} + \frac{x_2^2}{\xi}} = \sqrt{1} = 1$$

dunque  $\hat{\mathbf{n}}$  è la normale esterna alla superficie (statale).

Il flusso di calore è  $\hat{\mathbf{q}} \cdot \hat{\mathbf{n}} = \frac{1}{2} [x_1 (2x_1 t + x_3) + 3x_1 x_2 e^{-t}]$ .



(ii) Il verso è  $\hat{\mathbf{e}}_3$  e quindi  $\hat{\mathbf{q}} \cdot \hat{\mathbf{e}}_3 = 5(x_1^2 + x_2^2) + e^{-2t}$

valore totale è  $\pi x_3 = 7$  sì che  $\hat{\mathbf{q}} \cdot \hat{\mathbf{e}}_3 = 5(x_1^2 + x_2^2) + e^{-2t} \cdot \pi$

quindi il flusso totale è  $Q = \int \hat{\mathbf{q}} \cdot \hat{\mathbf{e}}_3 d\Omega = \int d\tau \int d\sigma d\theta \hat{\mathbf{q}} \cdot \hat{\mathbf{e}}_3 =$

$$= 5 + e^{-2t} \cdot 2\pi \sum_{n=0}^{\infty} r^3 dr = 5\pi e^{-2t} \cdot 2\pi \frac{r^4}{4} = 5\pi e^{-2t}.$$

(4.36) (i) La deformazione è la stessa dell'esempio (4.34) e quindi

$$\begin{aligned} Q &= F^{cr} \cdot \hat{\mathbf{q}} = \begin{pmatrix} (1+3t x_3^2) & 0 & (1-e^t) \\ 0 & 1 & (1-e^{2t}) \\ 0 & 0 & e^t \end{pmatrix} \begin{pmatrix} 2x_1 e^{-t} \\ 3x_2 e^{-t} \\ 5x_3 e^{-t} \end{pmatrix} = \\ &= \begin{pmatrix} 2x_1 e^{-t} (1+3t x_3^2) + 5x_3 e^{-t} (1-e^t) \\ 3x_2 e^{-t} + (1-e^{2t}) 5x_3 e^{-t} \\ 5x_3 e^{-t} \end{pmatrix} = \begin{pmatrix} 2((1+3t x_3^2)(x_1 + x_3(1-e^t))) \\ +5(e^{-t}-1)(x_3^3+x_3) \\ 3(1+3t x_3^2)(x_2 + x_3(e^{t}-e^{-t})) \\ +5(e^{-t}+e^t)(x_3^3+x_3) \end{pmatrix} \\ &= 5(x_3^3+x_3) \end{aligned}$$

$$(ii) \text{ If } h_2, \quad \phi = x_1 + x_2 \Rightarrow \nabla \phi = (1, 1, 0) \Rightarrow$$

$$\Rightarrow \hat{N} = \begin{pmatrix} \frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0 \end{pmatrix}. \quad \text{Value at } t=0 \text{ is } \begin{pmatrix} 1, -e^{-t}, 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -x_1 \\ x_2 \end{pmatrix}$$

$$= \begin{pmatrix} 2e^{-t} \\ -3e^{-2t} \\ 0 \end{pmatrix} \Rightarrow Q = \begin{pmatrix} 2e^{-t} \\ -3e^{-t} \\ 0 \end{pmatrix} \Rightarrow Q \cdot \hat{N} = \frac{\sqrt{2}}{2} e^{-t}$$

P. 81

$$\theta dS = \theta \frac{\partial S}{\partial F} dF + \theta \frac{\partial S}{\partial V} dV = \frac{\partial e}{\partial F} dF - \frac{I}{F} dF + \frac{\partial e}{\partial V} dV$$

$$= \left( \frac{\partial e}{\partial F} dF + \frac{\partial e}{\partial V} dV \right) - \frac{I}{F} dF = de - \frac{I}{F} dF$$

Helmholtz

$$d\psi = de - \theta dS - S d\theta = -S d\theta + \beta_m^{-1} S \cdot dE$$

$$d\psi = \frac{\partial \psi}{\partial \theta} d\theta + \frac{\partial \psi}{\partial E} dE$$

p. 85

## Elasticität Linde

23

$$\underline{\underline{T}} = \underline{\underline{F}} \underline{\underline{S}} \cong \underline{\underline{t}} \left[ \left( (1 + \frac{1}{2} \nu u) \underline{\underline{I}} - (\text{Grad } u)^\top \right) \right] = \\ = \underline{\underline{t}} + D \nu u \underline{\underline{t}} - \underline{\underline{t}} (\text{Grad } u)^\top \cong \underline{\underline{t}}$$

$$\underline{\underline{T}} = \underline{\underline{F}} \underline{\underline{S}} \quad \underline{\underline{S}} = \underline{\underline{F}}^{-1} \underline{\underline{T}} = \left( \underline{\underline{I}} - \text{Grad } u \right) \underline{\underline{T}} = \underline{\underline{T}} - \text{Grad } u \underline{\underline{T}} = \\ \cong \underline{\underline{t}} - (\text{Grad } u) \underline{\underline{t}} \cong \underline{\underline{t}}$$

$$\frac{\partial}{\partial x_A} = \frac{\partial}{\partial x_i} \frac{\partial x_i}{\partial X_A} = F_{iA} \frac{\partial}{\partial x_i} = \left( \underline{\underline{J}}_{iA} + (\text{Grad } u)_{iA} \right) \frac{\partial}{\partial x_i} =$$

$$= \frac{\partial}{\partial x_A} + \left( (\text{Grad } u)_{iA} \right) \frac{\partial}{\partial x_i} \quad \left| \begin{array}{l} \underline{\underline{F}} = \frac{1}{2} (\underline{\underline{C}} - \underline{\underline{I}}) = \frac{1}{2} (\underline{\underline{F}}^\top \underline{\underline{F}} - \underline{\underline{I}}) \end{array} \right.$$

p. 86

$$e(\underline{\underline{J}}_1, \underline{\underline{J}}_2, \underline{\underline{J}}_3) = e(0, 0, 0) + \left| \begin{array}{l} \underline{\underline{F}}(0) = \underline{\underline{I}}, \underline{\underline{E}}(0) = \frac{1}{2} (\underline{\underline{I}} - \underline{\underline{I}}) = 0 \end{array} \right.$$

$$+ \frac{\partial e}{\partial \underline{\underline{J}}_1|_0} \underline{\underline{J}}_1 + \frac{\partial e}{\partial \underline{\underline{J}}_2|_0} \underline{\underline{J}}_2 + \frac{\partial e}{\partial \underline{\underline{J}}_3|_0} \underline{\underline{J}}_3 + \frac{1}{2} \frac{\partial^2 e}{\partial \underline{\underline{J}}_1 \partial \underline{\underline{J}}_2|_0} \underline{\underline{J}}_1 \underline{\underline{J}}_2 + O(\varepsilon^3) = \\ = e(0, 0, 0) + \frac{\partial e}{\partial \underline{\underline{J}}_1|_0} (0, 0, 0) \underline{\underline{J}}_1 + \frac{\partial e}{\partial \underline{\underline{J}}_2|_0} (0, 0, 0) \underline{\underline{J}}_2 + \frac{1}{2} \frac{\partial^2 e}{\partial \underline{\underline{J}}_1^2|_0} \underline{\underline{J}}_1^2 + O(\varepsilon^3)$$

„0“ Punkt  $\underline{\underline{t}}(0) = \underline{\underline{0}}$ 

$$\underline{\underline{S}} = \underline{\underline{t}} = f^* \frac{\partial \underline{\underline{E}}}{\partial \underline{\underline{F}}} = f^* \left[ \frac{\partial e}{\partial \underline{\underline{J}}_1|_0} \underline{\underline{I}} + \frac{\partial e}{\partial \underline{\underline{J}}_2|_0} 2\underline{\underline{F}} + \frac{1}{2} \frac{\partial^2 e}{\partial \underline{\underline{J}}_1^2|_0} 2\underline{\underline{J}}_1 \underline{\underline{I}} + O(\varepsilon^2) \right] \\ \cong 2 \left( f^* \frac{\partial e}{\partial \underline{\underline{J}}_2|_0} \right) \underline{\underline{E}} + f^* \frac{\partial^2 e}{\partial \underline{\underline{J}}_1^2} (\text{tr } \underline{\underline{E}}) \underline{\underline{I}} = \boxed{\nu(\text{tr } \underline{\underline{E}}) \underline{\underline{I}} + 2M \underline{\underline{E}} \cong \underline{\underline{t}}}$$

$$\Rightarrow \mathcal{E} \equiv \frac{\nu}{2g} \mathfrak{J}_1^2 + \frac{\mu}{g} \mathfrak{J}_2 \quad , \text{ coh } V = g^* \frac{\partial e}{\partial \mathfrak{J}_2}|_0 \quad \mu = g^* \frac{\partial e}{\partial \mathfrak{J}_2}$$

$$Z = V + \frac{2}{3} \mu \quad \text{2 p 1}$$

$$\frac{\partial t_{ij}}{\partial x_j} = V \delta_{ij} \frac{\partial^2 u_k}{\partial x_k \partial x_j} + \mu \left( \frac{\partial^2 u_i}{\partial x_i \partial x_j} + \frac{\partial^2 u_j}{\partial x_i \partial x_j} \right)$$

$$= V \frac{\partial^2 u_k}{\partial x_k \partial x_i} + \mu \frac{\partial^2 u_i}{\partial x_i^2} + \mu \frac{\partial^2 u_k}{\partial x_k \partial x_i}$$

$$dr \stackrel{!}{=} (V + \mu) \nabla (dr \underline{u}) + \mu \Delta \underline{u}$$

$$\frac{\partial \underline{u}}{\partial t} = \underline{d} \exp(-iV) \quad (-iV), \quad \frac{\partial^2 \underline{u}}{\partial t^2} = (-iV)^2 \underline{d} \exp(-iV)$$

$$-V^2 \underline{u} = -V^2 \underline{d} \exp(-iV)$$

$$\frac{\partial \underline{u}_i}{\partial x_j} = \underline{d}_i \exp(-iV) i \frac{\partial (\underline{h}_k h_k)}{\partial x_j} = \underline{d}_i \exp(-iV) i \delta_{ki} h_k =$$

$$= \underline{d}_i \exp(-iV) i h_j = i (\underline{d} \otimes \hat{h})_{ij} \exp(-iV)$$

$$\frac{\partial^2 \underline{u}}{\partial x^2} = \nabla^2 \underline{u} = -(\underline{d} \otimes \hat{h} \otimes \hat{h}) \exp(-iV) = + \underline{u} \otimes \hat{h} \otimes \hat{h}$$

$$\Delta \underline{u} = -\underline{u} (\hat{h} \cdot \hat{h}) = -\underline{u}, \quad \nabla dr \underline{u} = -(\underline{h} \cdot \hat{h}) \hat{h}$$

$$-\rho V^2 \underline{u} + (\nu + \mu) (\underline{u} \cdot \hat{n}) \hat{n} + \mu \underline{u} = 0$$

$$(\rho V^2 - \mu) \underline{u} = (\nu + \mu) (\underline{u} \cdot \hat{n}) \hat{n}$$

$$(\rho V^2 - \mu) \underline{d} = (\nu + \mu) (\underline{d} \cdot \hat{n}) \hat{n}$$

$$V^2 = \frac{\mu}{\rho} \Leftrightarrow V = \pm \sqrt{\frac{\mu}{\rho}} \Rightarrow \mu > 0$$

→

Ej.: FdR caso dell'isotropia con onda piana  $x_1 + x_2 + x_3 = 0$ .

$$\text{Dm.: Si } h_1 = \frac{\sqrt{3}}{3} (1,1,1) \Rightarrow \underline{d} \cdot \hat{n} = 0 \Leftrightarrow (d_1 + d_2 + d_3) \frac{1}{3} = 0$$

$$\Rightarrow \underline{d}^1 = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}, \text{ e } \underline{d}^2 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}. \text{ onde transversali, mentre}$$

$$\underline{d}^3 = 2h = 2 \frac{\sqrt{3}}{3} (1,1,1) \text{ è longitudinale. Si } h_3 \text{ per la onda}$$

$$\text{transversale: } V_{\pm} = \pm \sqrt{\frac{\mu}{\rho}} = \pm \sqrt{\frac{77440}{7,86}} = \pm \sqrt{9852,42} \approx \pm 99,26$$

$$\text{mentre } V_{\pm}^3 = \pm \sqrt{\frac{\nu + 2\mu}{\rho}} = \pm \sqrt{\frac{2 + \frac{4}{3}\mu}{\rho}} = \pm \sqrt{\frac{150,300 + 77,400}{7,86}} = \pm \sqrt{32058,69} \approx \pm 179,67$$

$$\text{con } V = 2 - \frac{2}{3}\mu, \text{ cioè } V + 2\mu = 2 - \frac{2}{3}\mu + 2\mu = 2 + \frac{4}{3}\mu$$

e dunque il modulo di compressibilità  $\circledast$

densita.png

The screenshot shows a table titled "densita.png" with two columns. The first column is labeled "Materiale" and the second is "Densità a 20 °C (g/cm³)". The second column also includes a header "Densità a 20 °C e 1 atm (g/L)" for gases. The data is as follows:

Materiale	Densità a 20 °C (g/cm³)	Materiale	Densità a 20 °C e 1 atm (g/L)
acqua(a 4 °C)	1,00	aria	1,29
acciaio	7,86	azoto	1,25
alcool etilico	0,79	cloro	3,0
alluminio	2,7	elio	0,18
legno	da 0,8 a 0,9	idrogeno	0,089
olio di oliva	0,92	ossigeno	1,43

Costanti di Lamè Mezzo Continuo.jpg

The screenshot shows a table titled "Costanti di Lamè Mezzo Continuo.jpg" with four columns. The columns are labeled "Materiale", " $\lambda$ (MPa)", " $\mu$ (MPa)", and " $K$ (MPa)". The data is as follows:

Materiale	$\lambda$ (MPa)	$\mu$ (MPa)	$K$ (MPa)
Acciaio	150300	77440	202000
Alluminio	34300	26950	52270
Argento	22860	29100	42260
Ferro	82400	82400	137300
Piombo	11700	6000	15700
Rame	28300	46200	59150
Stagno	98800	16100	109500
Titanio	72860	44650	102630
Tungsteno	192900	151560	294000
Zinco	57100	38100	82500